

## Automatic stainless steel crimping machine

## **OPERATION INSTRUCTIONS**



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## **STATEMENT**

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#### 一、Preface

Thank you for purchasing and using the Automatic stainless steel crimping machine. This manual is the use and maintenance information of this equipment.

In order to ensure the safety of the operator and maintain the excellent performance of the equipment for a long time, before using the equipment, please read this manual carefully and save it for subsequent use to avoid danger or damage to the machine during operation.

This machine equipment is upgraded or updated at any time without notice, please understand! If you have any further technical or use problems, please contact our company in time.

#### 二、Product working conditions

### 2.1Working conditions

Ambient air range

Working hours 5  $\sim$ 40°C

During transportation and storage  $0^{\circ}$   $\sim$  40°  $\sim$ 

·Air relative humidity

At 35°C ≤50%

At 20°C ≤90%

- ·The content of dust, acid, corrosive gas and other substances in the surrounding air does not exceed the normal content.
  - ·The altitude does not exceed 1000 meters
  - ·Grid voltage fluctuation: ≤±10% (when the grid frequency is the rated value)
  - •Grid frequency fluctuation: ≤±1% (when the grid voltage is the rated value)



#### 2.2 Working environment

The product should be placed in a dry, ventilated and dust-free environment away from direct sunlight, rain, gas vapor, chemical deposition and corrosive media that seriously affect the use of the equipment, and avoid violent vibration and turbulence.

### 三、Safety Precautions

#### 3.1 Electricity safety

The basic principle of preventing electric shock is not to touch the two poles of voltage electrical equipment at the same time. The specific precautions are as follows:

- 1. Before operation, you must wear qualified protective equipment, such as safety gloves, insulating shoes, and all labor protection equipment must be dry and undamaged;
- 2. Before servicing and testing the equipment, cut off the power supply to prevent electric shock.

#### 3.2 Mechanical equipment hurts

When the equipment is working, be sure to keep hands, hair, clothing and tools away from mechanical movement, pneumatic actuators and other operating mechanisms. Pay attention to pneumatic and mechanical pressure components that hurt people. Operators are not allowed to wear loose clothing and accessories.

### 3.3Comprehensive preventive measures

- 1. Ensure equipment power safety measures;
- 2. Only skilled electricians can work on high-voltage equipment;
- 3. The equipment safety warning signs must have clear signs and be readily available;
- 4. During the operation of the equipment, the lubrication and maintenance of the equipment cannot be carried out.

### 3.4 Precautions for installation and debugging

- 1. After opening the package, confirm whether it is the model you ordered.
- 2.Check whether the equipment is damaged during transportation. If there is any damage, please contact our after-sales service.
  - 3. Our company will not bear any responsibility for equipment damage or other



losses caused by not strictly complying with the operating requirements specified in this manual.

4.After 7 days of installation and commissioning, our company cannot return the goods without reason.

5.Before installation and commissioning, please prepare 5 square meters of three-phase five-wire wires (the number of meters required according to your company's operating site), one 40A power switch, one bucket of purified water, about 20L, and several 10 mm air pipes. Compressed air less than 0.6MPa, steel strip materials, etc.

6.After installation and commissioning, our after-sales personnel will teach your company how to operate. Please be sure to send someone to study carefully.

### 四、Equipment introduction

#### 4.1Equipment picture:



### **4.2 Equipment introduction:**

The automatic crimping machine is based on the automatic laser welding machine, and the next process is continuous. It has the advantages of high efficiency, high quality, high energy saving, low cost, simple and convenient operation, and wide application range. It is ideal for the kitchenware production industry. Hemming



equipment. Below, we will elaborate on its operating principles, conditions of use, functions of each part, and daily maintenance.

- 1. The automatic crimping machine is an ideal special crimping equipment designed and manufactured by Ningbo Jinshihong Machinery Equipment Co., Ltd. according to the technical requirements of steel belts for kitchenware manufacturers;
- 2. The equipment has a wide range of applications, using touch screen digital input to control operation settings, simple and convenient operation, and easy to replace products;
- 3.Equipment accessories (panel racks, control systems, drive motors, pneumatic components) are all world-renowned brand products, and are equipped with high-precision planetary deceleration devices, which can improve the positioning accuracy of the product;
- 4. The equipment adopts programmable controller as the main control unit, the circuit is simple, highly integrated and intelligent, which reduces the failure rate and is convenient for maintenance and maintenance;
- 5. The crimping machine refers to moving the product steel ring to the crimping wheel to deform it to obtain the shape of the product crimping, and to achieve the required crimping by controlling the crimping speed, crimping depth, and the position of the crimping wheel. The effect, the advantage is that the mold replacement efficiency is fast, the operation is simple and the controllability is strong.

#### 4.3Equipment technical parameters:



| Name                    | Unit    | Technical parameters      |
|-------------------------|---------|---------------------------|
| Equipment size          | mm      | 1100*1500*2000            |
| Equipment weight        | kg      | 900                       |
| Two-step feeding size   | mm      | 1850*900*700              |
| Two-step feeding weight | kg      | 150                       |
| Total power             | KW      | 3                         |
| Required air pressure   | Мра     | 0.5~0.7                   |
| Input voltage           | V       | 380VThree-phase five-wire |
| Rated frequency         | HZ      | 50                        |
| External cable standard |         | 4*3+2.5*2 (U V W N PE)    |
| Crimping speed          | pcs/min | 8-12                      |

#### 4.4 Equipment features:

- 1. The steel ring welded by the welding machine is directly transferred to the crimping clamping and shaping station through the three-step feeding mechanism, and waiting for the next process of the crimping machine.
- 2. The up and down movement, back and forth movement, crimping wheel position and spindle rotation are all controlled by Huichuan servo motor to control the reclaiming position of steel ring. The depth and position of crimping are controlled by parameters. It has the advantages of high control precision, low failure rate and simple operation.
- 3. The crimping adopts four high material crimping wheels, which are completed and adjusted by four eccentric shafts, and the operation is simple and convenient.
- 4 The pneumatic components adopt Taiwan Yadeke and Japan SMC executive components, with long service life and high reliability.



#### 五、Maintain

### 5.1 Equipment maintenance:

- 1. All guide rails and screw rods shall be greased every six days, and the surface shall be cleaned before filling.
  - 2. Each piece of machinery shall not be loose once every three days.
- 3. Various faults encountered during commissioning shall be recorded, such as fault problems and solutions, so as to facilitate the next rapid processing.

#### **5.2 Daily maintenance:**

- 1.When working, the pressure of the gas source treatment unit must be adjusted to 0.5-0.6MPa
- 2. At least one filter drain operation should be carried out every shift (8 hours). Drainage method: cut off the gas source and treat the pressure gas in the two-piece air inlet and exhaust path. The pressure gauge value is 0. In this state, the filter automatically drains. After the operation is completed, it must be confirmed that the water collected in the filter has been discharged
- 3. Check the oil level of the oil cup of the oil feeder once a week to ensure that there is oil in the oil cup. The oil feeder uses isovg32 or lubricating oil of the same level. The oil output is adjusted by the knob above the oil feeder. It is recommended to adjust it to the number 2.
- 4. All the guide screw rods are greased every six days, and the surface must be cleaned before filling.

## 六、Common fault analysis and elimination

| Fault         | cause of issue                | resolvent                         |
|---------------|-------------------------------|-----------------------------------|
| phenomenon    |                               |                                   |
| No            |                               |                                   |
| response      | Power failure or phase loss   | Restore power                     |
| after startup |                               |                                   |
|               | Check whether the material is | Clear the alarm or re-power on    |
| Servo alarm   | jammed                        | according to the servo alarm code |



| Can't reset                          | <ol> <li>The origin switch is damaged and the welding station cannot be moved back.</li> <li>The device is in an alarm state.</li> </ol>   | 1. Check whether all cylinder switches are in place Replace the welding origin switch in time.  2. Clear alarm |
|--------------------------------------|--|--|
| Wrinkled<br>or flared steel<br>strip | <ul> <li>1 \ Incorrect position of crimping wheel</li> <li>2 \ The groove of crimping wheel is worn, resulting in uneven contact surface</li> </ul>  | the crimping wheel   |
| Uneven<br>crimping<br>depth          | The upper and lower cylinders of the crimping wheel are not in place, or the air pressure of the cylinder is too small     The chuck clamping cylinder cannot clamp the product steel belt |  |

### 七、Operation essentials

### 7.1 operational readiness:

- 1. Connect the air source to make the pressure gauge indicate 0.5-0.7 MPa.
- 2.Connect the 380V power supply, turn on the control box breaker switch, and turn on the emergency stop button on the lower panel to keep the machine energized.
- 3. When the cylinder servo motor is at the designated position, in the manual state, press any button on the manual screen on the screen to perform manual operation.
- 4. Automatic working conditions of the machine: the equipment does not have any alarms, the full axis reset is completed, and the equipment is in the automatic state.

### 7.2Cylinder magnetic switch position determination



- 1. When the cylinders are in the original position and in position, the corresponding induction switches will light up respectively.
  - 2. The position of the proximity switch is determined, please adjust as follows:
- (1) The machine is placed in the manual state, and the screen is also placed in the manual screen.
- (2) Press the cylinder button on the manual screen, and the corresponding cylinder will act to detect whether the sensor switch on the cylinder will be on. If it is not on, you can manually adjust it. If the manual adjustment is not on, the sensor switch may be broken or the line may be faulty.

Note: When any proximity switch is not inductive (not lit), the next action of the machine will not be carried out, and it will also cause damage to the equipment or product. At this time, special attention should be paid to maintenance or troubleshooting.

#### 八、Controller introduction

#### 8.1Features of the control system

The control system of the machine adopts Delta PLC, Fanyi touch screen and Huichuan servo driver. It can adjust the crimping depth, reclaiming position, crimping position and crimping speed, which is more convenient to control.

#### 8.2Introduction to touch screen button switch

On the premise of connecting the power supply, press the "emergency stop" button on the lower board of button 1, the work indicator on the panel is on and the touch screen is displayed.

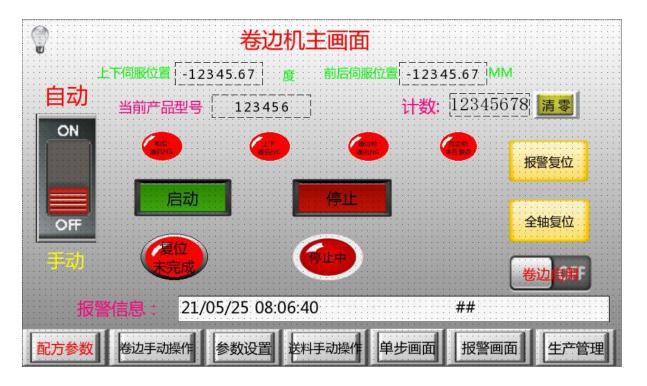
## Initial page-





After the machine is powered on, the initial state of the touch screen displays the startup screen, which displays the device name, company address, contact number, Chinese and English buttons in two languages, and the "Enter Operation" button.

## Main operation interface-





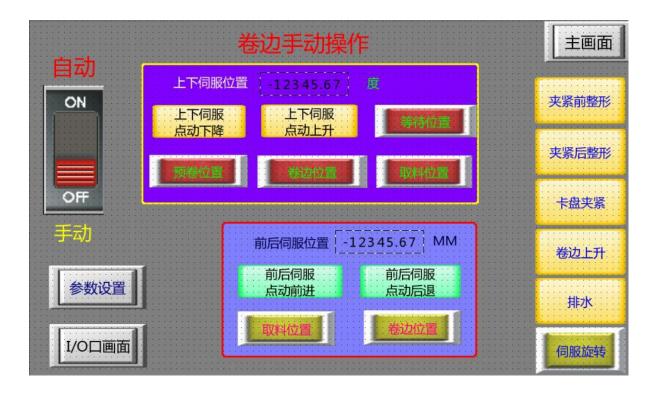
The host operates the touch screen to display the above screen. In the automatic state, the equipment does not have any alarms, and the equipment's full axis reset is completed, press the "start" button on the screen, and the machine can start normally. The corresponding sensor switch indicator light is also displayed on the screen, and the indicator light on the screen will be on. If it is not at the starting position, switch to manual, press the "reset" button, and the machine will automatically return to the starting position.

In the process of automatic operation, press the "Stop" button, the device will complete the current product, and run to the next round, the device will automatically stop. When the equipment fails, the corresponding alarm information will appear in the alarm information bar, which is very convenient for users to find out the corresponding fault in time. After the fault is handled, press the "Alarm Reset" button to clear the alarm information in the alarm information bar. If there is an alarm message such as a servo alarm, the device can handle the alarm message even if it is powered off and restarted.

In the main operation interface of the touch screen, press the "crimping manual operation" button, and the screen will jump to the manual screen. In the manual state, pressing any button on the manual screen will have corresponding action, such as "shaping before clamping" and "shaping after clamping", and the button indicator will be on during operation. Manual is only convenient for debugging, maintenance and use, and should be used less during normal production. Press the "upper and lower servo inching down" and "upper and lower servo inching up" buttons on the interface, the upper and lower servo will rise or fall, and the data of the upper and lower servo positions will change accordingly. Press the "front and rear servo inching forward" and "front and rear servo inching backward" buttons on the interface, the front and rear servo will move forward or backward, and the data of front and rear servo positions will change accordingly. Do not collide with other mechanical parts in the process of up and down servo and front and rear servo inching, so as to avoid damage to mechanical parts. Press the "waiting position", "pre winding position", "crimping position", "reclaiming position" and "crimping position" buttons on the interface, and the servo will run according to the parameters set in the parameter screen. Before these position buttons, ensure that the corresponding parameters in the parameter screen comply with the actual servo position to avoid collision and damage to mechanical parts.



## Manual page crimping-



In the main operation interface of the touch screen, press the "Manual feeding operation" button, the screen jumps to the manual operation screen of the hemming wheel, in the welding station operation screen of the touch screen, in the manual state, press "Pull 1 before and after", "Pull" in the interface Corresponding buttons such as "Material 1 Up and Down" and "Pulling Material 2 Front and Back" will have the cylinder act accordingly and the button indicator will light up. Press the interface "curling wheel jog forward" and "curling wheel jog backward" button, the hemming wheel will move forward or backward, and the current position data of the hemming wheel servo on the screen will also change accordingly. During the servo jog process, do not collide with other mechanical parts of the product to avoid damage to the mechanical parts. Press the interface "curling wheel in place" button, the hemming wheel will run to the manual position of the hemming wheel at the manual speed of the hemming wheel. It is often used in the process of adjusting the size of the hemming.



## Manual operation page with curling wheel-



Press the "Parameter Setting" button on the main screen, touch the screen to enter the parameter setting screen, as shown in the figure below.

## Parameters page-





The parameter page is to set the servo speed and cylinder delay parameters during the automatic operation of the crimping machine. The product length is set by the diameter of the steel ring that the user needs to weld, and the welding width is based on the width of the steel strip itself. To set. Press and hold the blank space in the lower right corner of the parameter setting screen, the touch screen will enter the welding machine parameter setting screen. As shown in the figure below, this screen is to set the speed and position of the servo operation during the welding process. When the equipment is debugged and stable, the welding machine The parameters of the parameter screen basically need to be changed. When the edge-drawing machine equipment connected in the subsequent process of the equipment, the edge-drawing machine needs to be turned on to realize the function of the curling and edge-drawing machine, and it needs to be set to turn on the edge-drawing machine.

## Host parameter setting 2.



·When the crimping machine needs to use multiple types of crimping, it needs to use the formula function. The formula can store the parameters of multiple models and specifications. During use, it can avoid the model of the used product to set the parameters again. Only need to retrieve the formula, change the mold, and then use it, which greatly saves the debugging time. The formula name can be English letters



and numbers, so that there will be no error in the next time the formula is called. When you want to store the currently used parameters in the recipe, set the name of the current recipe, click on the recipe box to use the recipe group number, click the "recipe upload" button, you can use the used parameter storage In the formula, it is very convenient to use at a time and can be directly recalled. When changing to a new model product and storing the formula before, you only need to click the "Formula Download" button to use it directly without setting parameters and adjusting the position again.

## Data display page-



In the event of a failure, it is necessary to re-debug or change to a new model of product, you can run the single-step mode, which is very convenient to find the problem points in the process of use. Click the "Single-Step Screen" button on the main screen to enter the single-step screen. In the device reset complete, no alarm, automatic mode, open the single-step screen "Run Mode" button, click the "Next" button, A single-step start of the device can be realized.



## Single step screen-



Click the "Production Management" button on the main screen to enter the output setting page, and you can see the product count and cumulative count. The set output means that the device can realize the automatic shutdown function when the product count reaches the set output value. When the output is set to 0, the shutdown function for output reaching is not enabled. Press the "Clear" button to clear the value of the product count, and also monitor the production beat, count per minute, current count, servo current position, and current status.



# Production management page-

| <b>生产管理</b> 日期:1234年12月12日<br>星期:日时间:12时 12分12秒 |       |      |                     |  |  |
|---|-------|------|---------------------|--|--|
| 生产节拍: 12.3 S                                    | 名称    | 当前状态 | 当前位置                |  |  |
| 累计计数: 12345678                                  | 上下伺服  |      | [-123.45] <b>mm</b> |  |  |
| 每分计数: 12 个/分                                    | 前后伺服  |      | [-123, 45] mm       |  |  |
| 当前计数: 12 个/分                                    | 卷边轮伺服 |      | [-123. 45] mm       |  |  |
| 计数: 123456                                      |       |      |                     |  |  |
| 清零  |       |      |                     |  |  |
|   |       |      |                     |  |  |

|              | 前后伺服参数   |              | 上下伺服参数       | li li       | 存转伺服参数       | 卷 ì            | <b></b><br>拉轮伺服参数  |
|--------------|--|--------------|--------------|-------------|--------------|----------------|--|
| H00-00=14101 | The same of the sa | H00-00=14101 | 电机编号         | H02-02=0    | 方向选择0-正转,1反转 | 1 Janes Cities | The second secon |
| H02-01=1     | 绝对值系统选择  | H02-01=1     | 绝对值系统选择      | H04-07=1    | 报警选择         | H02-01=1       | 绝对值系统选择  |
| H02-02=0     | 方向选择0-正转,1反转   | H02-02=0     | 方向选择0-正转,1反转 | H05-02=2000 | 1圈脉冲数        | H02-02=1       | 方向选择0-正转,1反  |
| H04-07=1     | 报警选择   | H04-07=1     | 报警选择         | H09-00=1    | 自调整模式选择      | H04-07=1       | 报警选择   |
| H05-02=3200  | 1圈脉冲数  | H05-02=2000  | 1圈脉冲数        | H09-01=15   | 刚性等级选择       | H05-02=4000    | 1圈脉冲数  |
| H09-00=1     | 自调整模式选择  | H09-00=1     | 自调整模式选择      | H03-11=1    | 伺服上电使能       | H09-00=1       | 自调整模式选择  |
| H09-01=15    | 刚性等级选择   | H09-01=15    | 刚性等级选择       | RUN         | 使能状态         | H09-01=15      | 刚性等级选择   |
| H0C-00=1     | 伺服轴地址  | H0C-00=2     | 伺服轴地址        | RDY         | 准备状态         | H0C-00=3       | 伺服轴地址  |
| H0C-02=2     | 串口波特率设置  | H0C-02=2     | 串口波特率设置      |             |              | H0C-02=2       | 串口波特率设置  |
| H0C-03=0     | MODBUS数据格式   | H0C-03=0     | MODBUS数据格式   |             |              | H0C-03=0       | MODBUS数据格式   |
| H03-11=1     | 伺服上电使能   | H03-11=1     | 伺服上电使能       |             |              | H03-11=1       | 伺服上电使能   |
| RUN          | 使能状态   | RUN          | 使能状态         |             |              | RUN            | 使能状态   |
| RDY          | 准备状态   | RDY          | 准备状态         |             |              | RDY            | 准备状态   |
| 1            | 专动轮伺服参数  |              |              |             |              |                |  |
| H02-00=0     | 控制模式选择0-速度模式   |              |              |             |              |                |  |
| H02-02=1     | 方向选择0-正转,1反转   |              |              |             |              |                |  |
| 104-07=1     | 报警选择   |              |              |             |              |                |  |
| H03-12=4     | DI6端子选择  |              |              |             |              |                |  |
| H03-14=6     | DI7端子选择  |              |              |             |              |                |  |
| H06-00=0     | H06-01=5   |              |              |             |              |                |  |
| H06-02=3     | H06-03=0   |              |              |             |              |                |  |
| H06-05=100   | H06-06=100   |              |              |             |              |                |  |
| H09-00=1     | 自调整模式选择  |              |              |             |              |                |  |
| H09-01=15    | 刚性等级选择   |              |              |             |              |                |  |
| H12-00=2     | H12-01=16  |              |              |             |              |                |  |
| 112-23=800   |  |              |              |             |              |                |  |
| 103-11=0     | 伺服上电使能   |              |              |             |              |                |  |